

Conformal Vector Fields on Lorentzian Lie Groups of Dimension 5

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Abstract. We classify Lorentzian Lie groups of dimension 5 which admit left-invariant non-Killing conformal vector fields.

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1. Introduction

Let (M, g) be a pseudo-Riemannian manifold. A vector field $X \in \Gamma(TM)$ is *conformal* if

$$L_X g = 2\rho g, \quad (1)$$

where L_X is the Lie derivation and ρ is a smooth function on M . If $\rho = 0$, we call X a *Killing* vector field which provides a close link between the geometry of a manifold M and the algebra of $I(M)$, the set of all isometries in M (see [13]). If g is a Riemannian metric, the existence of the function ρ might give some information about the topological structure of the Riemannian manifold (see [5, 12]).

To our knowledge, there are only a few results about the classification of left-invariant conformal vector fields on Lorentzian Lie groups which are Lie groups with left-invariant Lorentzian metrics. Firstly, the authors in [4] showed the existence of left-invariant conformal vector fields on three dimensional Lorentzian Lie groups. Then Araujo, Chen and Leandro proved a necessary condition for a Lorentzian Lie group to admit left-invariant non-Killing conformal vector fields and classified such Lorentzian Lie groups of dimension 2 and 3 in [2]. Also in [2], it was proved that there are some left-invariant non-Killing conformal vector fields on Lorentzian Lie groups in higher dimensions. In [7], Tan, Chen and Xu classified all Lorentzian Lie groups of dimension 4 admitting left-invariant non-Killing conformal vector fields. Recently left-invariant conformal Killing-Yano forms (a higher-degree generalization of conformal vector fields) have been treated by Andrada and Dotti in [1].

In this paper, we denote by \mathfrak{g} the Lie algebra of the connected Lie group G . It is clear that G is solvable if and only if \mathfrak{g} is solvable, so we can abuse them without

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ambiguity. We focus on Lorentzian Lie groups of dimension 5 admitting left-invariant non-Killing conformal vector fields, and first prove the following theorem.

Theorem 1.1. *Let G be a Lorentzian Lie group of dimension 5. If G admits a left-invariant non-Killing conformal vector field, then G is solvable.*

Finally, based on the discussion on solvable Lorentzian Lie groups of dimension 5, we get the classification theorem.

Theorem 1.2. *Let G be a Lorentzian Lie group of dimension 5 and \mathfrak{g} be the corresponding Lie algebra. If G admits a left-invariant non-Killing conformal vector field, then there is a basis $\{e_1, e_2, e_3, e_4, e_5\}$ of \mathfrak{g} such that $[\mathfrak{g}, \mathfrak{g}] = \text{span}\{e_1, e_2, e_3, e_4\}$, the Lorentzian metric associated with the basis is defined by*

$$\langle \cdot, \cdot \rangle = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix},$$

and the non-zero brackets are one of the following cases:

$$(1) \quad [e_1, e_2] = ke_4, \quad [e_2, e_3] = k\frac{\gamma}{\beta}e_4, \quad [e_1, e_5] = \alpha e_1 + \beta e_2 - \delta\left(1 - \frac{k\beta}{\alpha^2 + \gamma^2 + \beta^2}\right)e_4, \\ [e_2, e_5] = -\beta e_1 + \alpha e_2 + \gamma e_3 + \frac{k\alpha\delta}{\alpha^2 + \gamma^2 + \beta^2}e_4, \quad [e_3, e_5] = -\gamma e_2 + \alpha e_3 - \frac{k\gamma\delta}{\alpha^2 + \gamma^2 + \beta^2}e_4, \\ [e_4, e_5] = 2\alpha e_4, \quad \text{where } \gamma, \delta \text{ are arbitrary and } k\alpha\beta \neq 0.$$

For this case, the left-invariant non-Killing conformal vector field is a non-zero constant multiple of $\delta(\alpha^2 + \gamma^2)e_1 - \alpha\beta\delta e_2 + \gamma\beta\delta e_3 + \frac{\delta^2(\alpha^2 + \gamma^2)}{2\alpha}e_4 + \alpha(\alpha^2 + \gamma^2 + \beta^2)e_5$.

$$(2) \quad [e_2, e_3] = ke_4, \quad [e_1, e_5] = \alpha e_1 - \delta e_4, \quad [e_2, e_5] = \alpha e_2 + \gamma e_3, \quad [e_3, e_5] = -\gamma e_2 + \alpha e_3, \\ [e_4, e_5] = 2\alpha e_4, \quad \text{where } k\alpha\gamma\delta \neq 0. \quad \text{For this case, the left-invariant non-Killing conformal vector field is a non-zero constant multiple of } \delta e_1 + \frac{\delta^2}{2\alpha}e_4 + \alpha e_5.$$

$$(3) \quad [e_1, e_2] = le_4, \quad [e_1, e_3] = me_4, \quad [e_2, e_3] = ne_4, \quad [e_1, e_5] = \alpha e_1 - \delta e_4, \\ [e_2, e_5] = \alpha e_2 + l\frac{\delta}{\alpha}e_4, \quad [e_3, e_5] = \alpha e_3 + m\frac{\delta}{\alpha}e_4, \quad [e_4, e_5] = 2\alpha e_4, \quad \text{where } \delta \text{ is arbitrary and } \alpha(l^2 + m^2 + n^2) \neq 0. \\ \text{For this case, the left-invariant non-Killing conformal vector field is a non-zero constant multiple of } \delta e_1 + \frac{\delta^2}{2\alpha}e_4 + \alpha e_5.$$

$$(4) \quad [e_1, e_5] = \alpha e_1 + \beta e_2 - \delta e_4, \quad [e_2, e_5] = -\beta e_1 + \alpha e_2 + \gamma e_3, \quad [e_3, e_5] = -\gamma e_2 + \alpha e_3, \\ [e_4, e_5] = 2\alpha e_4, \quad \text{where } \gamma, \delta, \beta \text{ are arbitrary and } \alpha \neq 0. \quad \text{For this case, the left-invariant non-Killing conformal vector field is a non-zero constant multiple of } \delta(\alpha^2 + \gamma^2)e_1 - \alpha\beta\delta e_2 + \gamma\beta\delta e_3 + \frac{\delta^2(\alpha^2 + \gamma^2)}{2\alpha}e_4 + \alpha(\alpha^2 + \gamma^2 + \beta^2)e_5.$$

The paper is organized as follows. We recall some facts about left-invariant non-Killing conformal vector fields on pseudo-Riemannian Lie groups in Section 2. In Section 3, we prove that the Lorentzian Lie group of dimension 5 is solvable if it admits a left-invariant non-Killing conformal vector field. We devote Section 4 to classify five dimensional Lorentzian Lie groups G admitting left-invariant non-Killing conformal vector fields, i.e. Theorem 1.2.

2. Preliminaries

Let G be a Lie group with the Lie algebra \mathfrak{g} consisting of left-invariant vector fields and $\langle \cdot, \cdot \rangle$ be a pseudo-Riemannian metric on G . Let ∇ denote the Levi-Civita connection associated with $\langle \cdot, \cdot \rangle$.

Then $[X, Y] = \nabla_X Y - \nabla_Y X$. (2)

If $\langle \cdot, \cdot \rangle$ is left-invariant on G , we have

$$\langle \nabla_Z X, Y \rangle + \langle X, \nabla_Z Y \rangle = 0, \tag{3}$$

for any $X, Y, Z \in \mathfrak{g}$. By (2) and (3),

$$\langle \nabla_X Y, Z \rangle = \frac{1}{2}(\langle [X, Y], Z \rangle - \langle [Y, Z], X \rangle + \langle [Z, X], Y \rangle), \tag{4}$$

where X, Y, Z are left-invariant vector fields. Assume that $X \in \mathfrak{g}$ is a conformal vector field. By (1), we have $0 = L_X \langle X, X \rangle = 2\rho|X|^2$. It follows that any left-invariant non-Killing conformal vector field X is null, i.e., $\langle X, X \rangle = 0$. Moreover, if $\langle \cdot, \cdot \rangle$ is a Riemannian metric, then $\rho = 0$ or $X = 0$. That is, X is Killing or trivial. For the left-invariant pseudo-Riemannian metric $\langle \cdot, \cdot \rangle$, we have

Lemma 2.1 ([2]). *Let G be a unimodular pseudo-Riemannian Lie group. Then any left-invariant conformal vector field on G is a Killing vector field.*

If G is a non-unimodular pseudo-Riemannian Lie group, we have the following results.

Lemma 2.2 ([2]). *Let G be a Lorentzian Lie group admitting left-invariant non-Killing conformal vector fields. Then the restriction of $\langle \cdot, \cdot \rangle$ on $[\mathfrak{g}, \mathfrak{g}]$ is degenerate.*

Lemma 2.3 ([7]). *Let G be a Lorentzian Lie group admitting left-invariant non-Killing conformal vector fields. Then $\dim[\mathfrak{g}, \mathfrak{g}] = \dim \mathfrak{g} - 1$.*

From now on, we always suppose that G is a Lorentzian Lie group of dimension 5 with the Lie algebra \mathfrak{g} and G admits a left-invariant non-Killing conformal vector field. By Lemma 2.2 and Lemma 2.3, we know that there exists a basis $\{e_1, e_2, e_3, e_4, e_5\}$ of \mathfrak{g} such that $[\mathfrak{g}, \mathfrak{g}] = \text{span}\{e_1, e_2, e_3, e_4\}$. The matrix of the Lorentzian metric associated with this basis is defined by

$$\langle \cdot, \cdot \rangle = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix}. \tag{5}$$

Assume that X is a left-invariant non-Killing conformal vector field on G . Set $adX(e_j) = \sum_{i=1}^5 a_{ij}e_i, a_{ij} \in \mathbb{R}, i, j \in \{1, 2, 3, 4, 5\}$. Since the metric (5) is left-invariant, by (1), we have

$$\langle [X, e_i], e_j \rangle + \langle e_i, [X, e_j] \rangle = -2\rho \langle e_i, e_j \rangle.$$

where $0 \neq \rho \in \mathbb{R}$ is a constant. After a routine calculation, we know that the matrix of adX with respect to the basis $\{e_1, e_2, e_3, e_4, e_5\}$ is

$$\begin{pmatrix} -\rho & r_1 & r_2 & 0 & r_3 \\ -r_1 & -\rho & r_4 & 0 & r_5 \\ -r_2 & -r_4 & -\rho & 0 & r_6 \\ r_3 & r_5 & r_6 & -2\rho & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \tag{6}$$

where $r_i \in \mathbb{R}$, $i \in \{1, 2, 3, 4, 5, 6\}$. In the following we find another basis of \mathfrak{g} such that

- (1) the matrix of the metric under the basis is the same as (5),
- (2) the matrix of adX with respect to the basis is simpler.

Firstly, assume that r_3 , r_5 , r_6 are not all zero. Without loss of generality, we can assume $r_3 \neq 0$. Set $\tilde{e}_1 = \frac{1}{k}(e_1 + \frac{r_6}{r_3}e_3)$, $\tilde{e}_2 = e_2$, $\tilde{e}_3 = \frac{1}{k}(e_3 - \frac{r_6}{r_3}e_1)$, $\tilde{e}_4 = e_4$, $\tilde{e}_5 = e_5$, where $k = \sqrt{1 + (\frac{r_6}{r_3})^2}$. With respect to the basis $\{\tilde{e}_1, \tilde{e}_2, \tilde{e}_3, \tilde{e}_4, \tilde{e}_5\}$, the matrix of the metric is (5) and the matrix of adX is

$$\begin{pmatrix} -\rho & \frac{1}{k}(r_1 - \frac{r_6 r_4}{r_3}) & r_2 & 0 & \frac{1}{k}(r_3 + \frac{r_6^2}{r_3}) \\ -\frac{1}{k}(r_1 - \frac{r_6 r_4}{r_3}) & -\rho & \frac{1}{k}(r_4 + \frac{r_6 r_1}{r_3}) & 0 & r_5 \\ -r_2 & -\frac{1}{k}(r_4 + \frac{r_6 r_1}{r_3}) & -\rho & 0 & 0 \\ \frac{1}{k}(r_3 + \frac{r_6^2}{r_3}) & r_5 & 0 & -2\rho & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

Denote $\{\tilde{e}_1, \tilde{e}_2, \tilde{e}_3, \tilde{e}_4, \tilde{e}_5\}$ by $\{e_1, e_2, e_3, e_4, e_5\}$, the matrix of adX with respect to the basis $\{e_1, e_2, e_3, e_4, e_5\}$ is of the form

$$\begin{pmatrix} -\rho & r_1 & r_2 & 0 & r_3 \\ -r_1 & -\rho & r_4 & 0 & r_5 \\ -r_2 & -r_4 & -\rho & 0 & 0 \\ r_3 & r_5 & 0 & -2\rho & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}. \quad (7)$$

Secondly, assume that r_3 , r_5 are not all zero. Without loss of generality, we can assume $r_3 \neq 0$. Set $\tilde{e}_1 = \frac{1}{k}(e_1 + \frac{r_5}{r_3}e_2)$, $\tilde{e}_2 = \frac{1}{k}(e_2 - \frac{r_5}{r_3}e_1)$, $\tilde{e}_3 = e_3$, $\tilde{e}_4 = e_4$, $\tilde{e}_5 = e_5$, where $k = \sqrt{1 + (\frac{r_5}{r_3})^2}$. With respect to the basis $\{\tilde{e}_1, \tilde{e}_2, \tilde{e}_3, \tilde{e}_4, \tilde{e}_5\}$, the matrix of the metric is (5) and the matrix of adX is

$$\begin{pmatrix} -\rho & r_1 & \frac{1}{k}(r_2 + \frac{r_5 r_4}{r_3}) & 0 & \frac{1}{k}(r_3 + \frac{r_5^2}{r_3}) \\ -r_1 & -\rho & \frac{1}{k}(r_4 - \frac{r_5 r_2}{r_3}) & 0 & 0 \\ -\frac{1}{k}(r_2 + \frac{r_5 r_4}{r_3}) & -\frac{1}{k}(r_4 - \frac{r_5 r_2}{r_3}) & -\rho & 0 & 0 \\ \frac{1}{k}(r_3 + \frac{r_5^2}{r_3}) & 0 & 0 & -2\rho & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

Denote $\{\tilde{e}_1, \tilde{e}_2, \tilde{e}_3, \tilde{e}_4, \tilde{e}_5\}$ by $\{e_1, e_2, e_3, e_4, e_5\}$, the matrix of adX with respect to the basis $\{e_1, e_2, e_3, e_4, e_5\}$ is of the form

$$\begin{pmatrix} -\rho & r_1 & r_2 & 0 & r_3 \\ -r_1 & -\rho & r_4 & 0 & 0 \\ -r_2 & -r_4 & -\rho & 0 & 0 \\ r_3 & 0 & 0 & -2\rho & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}. \quad (8)$$

Lastly, assume that r_1 , r_2 are not all zero. Without loss of generality, we can assume $r_1 \neq 0$. Set $\tilde{e}_1 = e_1$, $\tilde{e}_2 = \frac{1}{k}(e_2 + \frac{r_2}{r_1}e_3)$, $\tilde{e}_3 = \frac{1}{k}(e_3 - \frac{r_2}{r_1}e_2)$, $\tilde{e}_4 = e_4$, $\tilde{e}_5 = e_5$, where

$k = \sqrt{1 + (\frac{r_2}{r_1})^2}$. With respect to the basis $\{\tilde{e}_1, \tilde{e}_2, \tilde{e}_3, \tilde{e}_4, \tilde{e}_5\}$, the matrix of the metric is (5) and the matrix of adX is

$$\begin{pmatrix} -\rho & \frac{1}{k}(r_1 + \frac{r_2^2}{r_1}) & 0 & 0 & r_3 \\ -\frac{1}{k}(r_1 + \frac{r_2^2}{r_1}) & -\rho & r_4 & 0 & 0 \\ 0 & -r_4 & -\rho & 0 & 0 \\ r_3 & 0 & 0 & -2\rho & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

In summary, there is a basis $\{e_1, e_2, e_3, e_4, e_5\}$ of \mathfrak{g} with $[\mathfrak{g}, \mathfrak{g}] = \text{span}\{e_1, e_2, e_3, e_4\}$, the matrix of the Lorentzian metric is unchanged, while the matrix of adX is

$$\begin{pmatrix} -\rho & \lambda & 0 & 0 & \theta \\ -\lambda & -\rho & \eta & 0 & 0 \\ 0 & -\eta & -\rho & 0 & 0 \\ \theta & 0 & 0 & -2\rho & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \tag{9}$$

where $\lambda, \theta, \eta \in \mathbb{R}$. Then we can write the left-invariant non-Killing conformal field X as

$$X = x_1e_1 + x_2e_2 + x_3e_3 + x_4e_4 + x_5e_5, \tag{10}$$

where $x_i \in \mathbb{R}$. Using Jacobi identity and (9), we get the following important equations

$$adX([e_1, e_2]) = -2\rho[e_1, e_2] - \eta[e_1, e_3] - \theta[e_2, e_4], \tag{11}$$

$$adX([e_1, e_3]) = -2\rho[e_1, e_3] + \eta[e_1, e_2] - \lambda[e_2, e_3] - \theta[e_3, e_4], \tag{12}$$

$$adX([e_2, e_3]) = -2\rho[e_2, e_3] + \lambda[e_1, e_3], \tag{13}$$

$$adX([e_1, e_4]) = -3\rho[e_1, e_4] - \lambda[e_2, e_4], \tag{14}$$

$$adX([e_2, e_4]) = -3\rho[e_2, e_4] + \lambda[e_1, e_4] - \eta[e_3, e_4], \tag{15}$$

$$adX([e_3, e_4]) = -3\rho[e_3, e_4] + \eta[e_2, e_4]. \tag{16}$$

By (9), the characteristic polynomial of adX on $[\mathfrak{g}, \mathfrak{g}]$ is

$$f(x) = (x + \rho)(x + 2\rho)((x + \rho)^2 + \lambda^2 + \eta^2).$$

So the real eigenvalues of adX on $[\mathfrak{g}, \mathfrak{g}]$ are $-\rho$ and -2ρ . If $\lambda^2 + \eta^2 \neq 0$, it is easy to see that the eigenspaces of adX on $[\mathfrak{g}, \mathfrak{g}]$ are

$$V_{-\rho} = \text{span}\{\eta e_1 + \lambda e_3 + \frac{\theta\eta}{\rho} e_4\}, \quad V_{-2\rho} = \text{span}\{e_4\};$$

if $\lambda^2 + \eta^2 = 0$, the eigenspaces of adX on $[\mathfrak{g}, \mathfrak{g}]$ are

$$V_{-\rho} = \text{span}\{e_1 + \frac{\theta}{\rho} e_4, e_2, e_3\}, \quad V_{-2\rho} = \text{span}\{e_4\}.$$

3. The proof of Theorem 1.1

This section aims at proving Theorem 1.1. Consider the Levi decomposition of \mathfrak{g}

$$\mathfrak{g} = \mathfrak{s} \ltimes \mathfrak{r}, \quad (17)$$

where \mathfrak{s} is a semisimple Lie subalgebra and \mathfrak{r} is the radical. Since \mathfrak{g} is of dimension 5, we only need to consider two kinds, i.e., $\mathfrak{g} = \mathfrak{r}$ is solvable or $\dim \mathfrak{s} = 3$, \mathfrak{s} is simple. If $\dim \mathfrak{s} = 3$, then $\dim \mathfrak{r} = 2$. Since \mathfrak{r} is solvable, it is well-known that \mathfrak{r} is either defined by $[x, y] = 0$ or defined by $[x, y] = x$, where $\{x, y\}$ is a basis of \mathfrak{r} . If $[x, y] = 0$, it is easy to see that \mathfrak{g} is unimodular, by Lemma 2.1, we know that \mathfrak{g} admits no left-invariant non-Killing conformal vector fields.

Lemma 3.1. *If \mathfrak{r} is defined by $[x, y] = x$, then all derivations of \mathfrak{r} are inner and $\mathfrak{g} = \mathfrak{s} \oplus \mathfrak{r}$ is a direct sum of ideals.*

Proof. Let $\sigma \in \text{Der}(\mathfrak{r})$ be any derivation of \mathfrak{r} , and suppose

$$\sigma(x, y) = (x, y) \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix},$$

then by $\sigma([x, y]) = [\sigma(x), y] + [x, \sigma(y)]$, we conclude that $a_{21} = a_{22} = 0$. It is easy to verify that $\sigma = a_{12}ad_{\mathfrak{r}}x - a_{11}ad_{\mathfrak{r}}y$, hence σ is inner, so the first statement is proved.

For the second statement, we consider the following representation of \mathfrak{s}

$$\varphi: \mathfrak{s} \rightarrow \mathfrak{gl}(\mathfrak{r}), \quad z \mapsto (ad_{\mathfrak{g}}z)|_{\mathfrak{r}}$$

Since \mathfrak{s} is simple, we have that $\varphi(\mathfrak{s}) = 0$ or $\varphi(\mathfrak{s})$ is simple. Notice that for any $z \in \mathfrak{s}$, $\varphi(z)$ is a derivation of \mathfrak{r} , then by the proof of the first statement, we know

$$\varphi(\mathfrak{s}) \subset \left\{ \begin{pmatrix} c_1 & c_2 \\ 0 & 0 \end{pmatrix} : c_1, c_2 \in \mathbb{R} \right\},$$

with respect to the basis $\{x, y\}$ of \mathfrak{r} . That is $\dim \varphi(\mathfrak{s}) \leq 2$, so we must have $\varphi(\mathfrak{s}) = 0$, i.e. $\mathfrak{g} = \mathfrak{s} \oplus \mathfrak{r}$ is a direct sum of ideals. \blacksquare

By Lemma 3.1, we have $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{s} \oplus \text{span}\{x\}$ with the center $\text{span}\{x\}$. Then, it is clear that $adX(x) = cx$ for some $c \in \mathbb{R}$. Namely the center of $[\mathfrak{g}, \mathfrak{g}]$ are eigenvectors of adX . In the following, we split (9) into two cases: $\lambda^2 + \eta^2 = 0$ and $\lambda^2 + \eta^2 \neq 0$.

Case 1. $\lambda^2 + \eta^2 = 0$. In this case, the eigenvalues of adX on $[\mathfrak{g}, \mathfrak{g}]$ are $-\rho$ and -2ρ , then by (14), (15) and (16), we know that $[e_1, e_4] = [e_2, e_4] = [e_3, e_4] = 0$; by (11), (12) and (13), we know that $[e_1, e_2], [e_1, e_3], [e_2, e_3] \in V_{-2\rho}$. Since we have $\mathfrak{g}^{(2)} = \text{span}\{[e_i, e_j]\}_{1 \leq i, j \leq 4}$, it follows that $\dim \mathfrak{g}^{(2)} \leq 1$, which contradicts $\dim \mathfrak{g}^{(2)} = 3$.

Case 2. $\lambda^2 + \eta^2 \neq 0$. The center of $[\mathfrak{g}, \mathfrak{g}]$ is either $V_{-\rho} = \text{span}\{\eta e_1 + \lambda e_3 + \frac{\eta\theta}{\rho} e_4\}$ or $V_{-2\rho} = \text{span}\{e_4\}$ in this case. If $V_{-2\rho} = \text{span}\{e_4\}$ is the center of $[\mathfrak{g}, \mathfrak{g}]$, then $[e_1, e_4] = [e_2, e_4] = [e_3, e_4] = 0$. Since $\mathfrak{g}^{(2)} = \text{span}\{[e_i, e_j]\}_{1 \leq i, j \leq 4}$ and $\dim \mathfrak{g}^{(2)} = 3$, it follows that $[\mathfrak{g}, \mathfrak{g}] = \text{span}\{[e_1, e_2], [e_1, e_3], [e_2, e_3]\} \oplus \text{span}\{e_4\}$. By (11), (12) and (13), it is easy to see that $\text{Trace}(adX|_{[\mathfrak{g}, \mathfrak{g}]}) = -8\rho$. But from (9) we know that $\text{Trace}(adX|_{[\mathfrak{g}, \mathfrak{g}]}) = -5\rho$, hence $\rho = 0$, which is a contradiction.

Therefore, $V_{-\rho} = \text{span}\{\eta e_1 + \lambda e_3 + \frac{\eta\theta}{\rho} e_4\}$ is the center of $[\mathfrak{g}, \mathfrak{g}]$. If $\eta = 0$, then $V_{-\rho} = \text{span}\{e_3\}$, so $[e_1, e_3] = [e_2, e_3] = [e_3, e_4] = 0$. Similarly, it is easy to see that $\text{Trace}(adX|_{[\mathfrak{g}, \mathfrak{g}]}) = -9\rho$ by (11), (14) and (15), which is a contradiction. If $\eta \neq 0$, by (24), (25), (26), we directly get $\text{Trace}(adX|_{[\mathfrak{g}, \mathfrak{g}]}) = -9\rho$, which is also a contradiction. This completes the proof of Theorem 1.1.

4. The proof of Theorem 1.2

By Theorem 1.1, it is enough to study the case that \mathfrak{g} is a solvable Lie algebra of dimension 5. By Lemma 2.3, $[\mathfrak{g}, \mathfrak{g}]$ is a nilpotent Lie algebra of dimension 4. It is known that a four-dimensional nilpotent Lie algebra is one of the three types of Table 1 (see [8, 15]).

Table 1: Four-dimensional nilpotent Lie algebras

Type	Basis	Non-zero Brackets	Center
1	$\{y_1, y_2, y_3, y_4\}$	$[y_1, y_2] = y_3$	$\text{span}\{y_3, y_4\}$
2	$\{y_1, y_2, y_3, y_4\}$	none	$\text{span}\{y_1, y_2, y_3, y_4\}$
3	$\{y_1, y_2, y_3, y_4\}$	$[y_1, y_2] = y_3, [y_1, y_3] = y_4$	$\text{span}\{y_4\}$

We will complete Theorem 1.2 by three subsections based on the type of $[\mathfrak{g}, \mathfrak{g}]$.

4.1. $[\mathfrak{g}, \mathfrak{g}]$ is of Type 1 in Table 1

We know that $[\mathfrak{g}, \mathfrak{g}] = \text{span}\{e_1, e_2, e_3, e_4\} = \text{span}\{y_1, y_2, y_3, y_4\}$, and the 2-step derived algebra $\mathfrak{g}^{(2)} = \text{span}\{[e_i, e_j]_{1 \leq i, j \leq 4}\} = \text{span}\{y_3\}$ is of dimension 1 and it is contained in the center of $[\mathfrak{g}, \mathfrak{g}]$. Clearly $adX(y_3) = cy_3$ for some $c \in \mathbb{R}$, so elements of $\mathfrak{g}^{(2)}$ are eigenvectors of adX . In the following, we will discuss two cases: $\lambda^2 + \eta^2 \neq 0$ and $\lambda^2 + \eta^2 = 0$.

Case 1: $\lambda^2 + \eta^2 \neq 0$.

Lemma 4.1. *Let the notations be as above. Then e_4 lies in the center of $[\mathfrak{g}, \mathfrak{g}]$.*

Proof. Suppose $[e_1, e_4] \neq 0$, then $\mathfrak{g}^{(2)} = \text{span}\{[e_1, e_4]\}$. Since $[e_1, e_4]$ is an eigenvector of adX , we have

$$adX([e_1, e_4]) = -3\rho[e_1, e_4] - \lambda[e_2, e_4] = -2\rho[e_1, e_4], \tag{18}$$

or
$$adX([e_1, e_4]) = -3\rho[e_1, e_4] - \lambda[e_2, e_4] = -\rho[e_1, e_4]. \tag{19}$$

If (18) is true, then $\lambda[e_2, e_4] = -\rho[e_1, e_4]$. Using this relation and (15), (18), we can easily get the following equation

$$\begin{aligned} (adX)^2([e_1, e_4]) &= -3\rho(-3\rho[e_1, e_4] - \lambda[e_2, e_4]) - \lambda(-3\rho[e_2, e_4] + \lambda[e_1, e_4] - \eta[e_3, e_4]) \\ &= 9\rho^2[e_1, e_4] - 3\rho^2[e_1, e_4] - 3\rho^2[e_1, e_4] - \lambda^2[e_1, e_4] + \lambda\eta[e_3, e_4] \\ &= (3\rho^2 - \lambda^2)[e_1, e_4] + \lambda\eta[e_3, e_4] = 4\rho^2[e_1, e_4], \end{aligned}$$

then $\lambda\eta[e_3, e_4] = (\rho^2 + \lambda^2)[e_1, e_4]$. Using this relation and (16), (18), we have

$$\begin{aligned} (adX)^3([e_1, e_4]) &= (3\rho^2 - \lambda^2)(-3\rho[e_1, e_4] - \lambda[e_2, e_4]) + \lambda\eta(-3\rho[e_3, e_4] + \eta[e_2, e_4]) \\ &= (-9\rho^3 - \rho\lambda^2 - \rho\eta^2)[e_1, e_4] = (-8\rho^3)[e_1, e_4]. \end{aligned}$$

It follows that $-\rho^2 = \lambda^2 + \eta^2 > 0$, which is absurd. Following the same reasoning, one can easily show that (19) is also impossible. This means $[e_1, e_4] = 0$. Similarly, one can show $[e_3, e_4] = 0$.

Combining $[e_1, e_4] = [e_3, e_4] = 0$ with (15), we have $adX([e_2, e_4]) = -3\rho[e_2, e_4]$. Since the real eigenvalues of adX on $[\mathfrak{g}, \mathfrak{g}]$ are $-\rho$ and -2ρ , we conclude $[e_2, e_4] = 0$. So e_4 lies in the center of $[\mathfrak{g}, \mathfrak{g}]$. ■

Lemma 4.2. *Let the notations be as above. Then $[e_1, e_3] = 0$ and $\eta[e_1, e_2] = \lambda[e_2, e_3]$.*

Proof. We first claim $\lambda[e_1, e_3] = 0$. Suppose $\lambda[e_1, e_3] \neq 0$, we have $adX([e_2, e_3]) = -2\rho[e_2, e_3] + \lambda[e_1, e_3]$ by (13). Clearly, $[e_2, e_3] \neq 0$ (otherwise, it contradicts the initial assumption), since elements of $\mathfrak{g}^{(2)} = \text{span}\{[e_i, e_j]\}_{1 \leq i, j \leq 4}$ are eigenvectors of adX , we know $[e_2, e_3]$ is an eigenvector of adX . Then either $adX([e_2, e_3]) = -\rho[e_2, e_3]$ or $adX([e_2, e_3]) = -2\rho[e_2, e_3]$. If the former is true, one can easily follow the proof of Lemma 4.1 to get $-\rho^2 = \lambda^2 + \eta^2 > 0$, which is absurd; if the latter is true, we have $\lambda[e_1, e_3] = 0$, which contradicts the initial assumption. So $\lambda[e_1, e_3] = 0$, the claim is proved.

Similarly one can prove $\eta[e_1, e_3] = 0$ by Lemma 4.1 and (11). Since $\lambda^2 + \eta^2 \neq 0$, we must have $[e_1, e_3] = 0$. Then by Lemma 4.1 and (12), we have $\eta[e_1, e_2] = \lambda[e_2, e_3]$. ■

After these preparations we can discuss further:

(★) $\lambda \neq 0$. For this case, by Lemma 4.1, Lemma 4.2 and (11), there is a non-zero constant $k \in \mathbb{R}$ such that $[e_1, e_2] = ke_4$, $[e_2, e_3] = k\frac{\eta}{\lambda}e_4$. Using (9) and (10), we have

$$\begin{aligned} (adX)(e_1) &= [x_1e_1 + x_2e_2 + x_3e_3 + x_4e_4 + x_5e_5, e_1] = -kx_2e_4 + x_5[e_5, e_1] \\ &= -\rho e_1 - \lambda e_2 + \theta e_4. \end{aligned}$$

Since $\rho \neq 0$, we know $x_5 \neq 0$. So

$$[e_1, e_5] = \frac{1}{x_5} \{ \rho e_1 + \lambda e_2 - (\theta + kx_2)e_4 \}.$$

Similarly,
$$[e_2, e_5] = \frac{1}{x_5} \{ -\lambda e_1 + \rho e_2 + \eta e_3 + k(x_1 - x_3\frac{\eta}{\lambda})e_4 \},$$

$$[e_3, e_5] = \frac{1}{x_5} \{ -\eta e_2 + \rho e_3 + kx_2\frac{\eta}{\lambda}e_4 \},$$

$$[e_4, e_5] = \frac{1}{x_5} \{ 2\rho e_4 \}.$$

We know $adX(e_5) = \sum_{i=1}^4 x_i[e_i, e_5] = \theta e_1$ by (9), and using those brackets above, we can easily get the following identities:

$$x_1 = \frac{\theta(\rho^2 + \eta^2)}{\rho(\rho^2 + \eta^2 + \lambda^2)}x_5, \quad x_2 = \frac{-\lambda\theta}{(\rho^2 + \eta^2 + \lambda^2)}x_5, \quad x_3 = \frac{\eta\lambda\theta}{\rho(\rho^2 + \eta^2 + \lambda^2)}x_5, \quad x_4 = \frac{\theta^2(\rho^2 + \eta^2)}{2\rho^2(\rho^2 + \lambda^2 + \eta^2)}x_5.$$

Define $\alpha = \frac{\rho}{x_5}$, $\beta = \frac{\lambda}{x_5}$, $\gamma = \frac{\eta}{x_5}$, $\delta = \frac{\theta}{x_5}$. The non-zero brackets of \mathfrak{g} are

$$[e_1, e_2] = ke_4, \quad [e_2, e_3] = k\frac{\gamma}{\beta}e_4,$$

$$[e_1, e_5] = \alpha e_1 + \beta e_2 - \delta \left(1 - \frac{k\beta}{\alpha^2 + \gamma^2 + \beta^2} \right) e_4,$$

$$[e_2, e_5] = -\beta e_1 + \alpha e_2 + \gamma e_3 + \frac{k\alpha\delta}{\alpha^2 + \gamma^2 + \beta^2} e_4,$$

$$[e_3, e_5] = -\gamma e_2 + \alpha e_3 - \frac{k\gamma\delta}{\alpha^2 + \gamma^2 + \beta^2} e_4,$$

$$[e_4, e_5] = 2\alpha e_4,$$

where γ, δ are arbitrary and $k\alpha\beta \neq 0$. Then the left-invariant non-Killing conformal vector field is a non-zero constant multiple of

$$\delta(\alpha^2 + \gamma^2)e_1 - \alpha\beta\delta e_2 + \gamma\beta\delta e_3 + \frac{\delta^2(\alpha^2 + \gamma^2)}{2\alpha}e_4 + \alpha(\alpha^2 + \gamma^2 + \beta^2)e_5.$$

This is case (1) of Theorem 1.2.

(\blacklozenge) $\lambda = 0$. Since $\lambda^2 + \eta^2 \neq 0$, for this case, we have $\eta \neq 0$, moreover, we can require $\delta \neq 0$ because $\lambda = \delta = 0, \eta \neq 0$ is equivalent to $\eta = \delta = 0, \lambda \neq 0$ in (\blackstar) after reordering the basis. By Lemma 4.1, Lemma 4.2 and (13), there is a constant $k \neq 0$ such that $[e_2, e_3] = ke_4, [e_1, e_2] = 0$. Following the same procedure of (\blackstar), we can get the non-zero brackets of \mathfrak{g} as

$$\begin{aligned} [e_2, e_3] &= ke_4, & [e_1, e_5] &= \alpha e_1 - \delta e_4, & [e_2, e_5] &= \alpha e_2 + \gamma e_3, \\ [e_3, e_5] &= -\gamma e_2 + \alpha e_3, & [e_4, e_5] &= 2\alpha e_4, \end{aligned}$$

where $k\alpha\gamma\delta \neq 0$. Then the left-invariant non-Killing conformal vector field is a non-zero constant multiple of $\delta e_1 + \frac{\delta^2}{2\alpha}e_4 + \alpha e_5$. This is case (2) of Theorem 1.2.

Case 2: $\lambda^2 + \eta^2 = 0$.

Recall that the only real eigenvalues of adX on $[\mathfrak{g}, \mathfrak{g}]$ are $-\rho$ and -2ρ . By (14), (15) and (16), $[e_1, e_4] = [e_2, e_4] = [e_3, e_4] = 0$. Then by (11), (12) and (13), $[e_1, e_2], [e_1, e_3], [e_2, e_3] \in V_{-2\rho}$, which means there exist $l, m, n \in \mathbb{R}, l^2 + m^2 + n^2 \neq 0$ such that $[e_1, e_2] = le_4, [e_1, e_3] = me_4, [e_2, e_3] = ne_4$. In the same way with (\blackstar), we can get the non-zero brackets of \mathfrak{g} as

$$\begin{aligned} [e_1, e_2] &= le_4, & [e_1, e_3] &= me_4, & [e_2, e_3] &= ne_4, & [e_1, e_5] &= \alpha e_1 - \delta e_4 \\ [e_2, e_5] &= \alpha e_2 + l\frac{\delta}{\alpha}e_4, & [e_3, e_5] &= \alpha e_3 + m\frac{\delta}{\alpha}e_4, & [e_4, e_5] &= 2\alpha e_4, \end{aligned}$$

where δ is arbitrary and $\alpha(l^2 + m^2 + n^2) \neq 0$. The left-invariant non-Killing conformal vector field is a non-zero constant multiple of $\delta e_1 + \frac{\delta^2}{2\alpha}e_4 + \alpha e_5$. This is the case (3) of Theorem 1.2.

4.2. $[\mathfrak{g}, \mathfrak{g}]$ is of Type 2 in Table 1

Following the procedure of (\blackstar) again we calculate the non-zero brackets of \mathfrak{g} as

$$\begin{aligned} [e_1, e_5] &= \alpha e_1 + \beta e_2 - \delta e_4, & [e_2, e_5] &= -\beta e_1 + \alpha e_2 + \gamma e_3, \\ [e_3, e_5] &= -\gamma e_2 + \alpha e_3, & [e_4, e_5] &= 2\alpha e_4, \end{aligned}$$

where γ, δ, β are arbitrary and $\alpha \neq 0$. Then the left-invariant non-Killing conformal vector field is a non-zero constant multiple of

$$\delta(\alpha^2 + \gamma^2)e_1 - \alpha\beta\delta e_2 + \gamma\beta\delta e_3 + \frac{\delta^2(\alpha^2 + \gamma^2)}{2\alpha}e_4 + \alpha(\alpha^2 + \gamma^2 + \beta^2)e_5.$$

This is case (4) of Theorem 1.2.

4.3. $[\mathfrak{g}, \mathfrak{g}]$ is of Type 3 in Table 1

For this case, we will show \mathfrak{g} admits no left-invariant non-Killing conformal vector fields. We first prove a simple lemma as follows.

Lemma 4.3. *Any inner derivation of \mathfrak{g} leaves the center of $[\mathfrak{g}, \mathfrak{g}]$ invariant.*

Proof. For any $X, U, V \in \mathfrak{g}$ and Y in the center of $[\mathfrak{g}, \mathfrak{g}]$ we get by Jacobi's identity:

$$[[U, V], [X, Y]] = [[[U, V], X], Y] + [X, [[U, V], Y]] = 0.$$

Hence $[X, Y]$ lies in the center of $[\mathfrak{g}, \mathfrak{g}]$, which means adX leaves the center of $[\mathfrak{g}, \mathfrak{g}]$ invariant and the Lemma is proved. ■

By Table 1, we know that $[\mathfrak{g}, \mathfrak{g}] = \text{span}\{e_1, e_2, e_3, e_4\} = \text{span}\{y_1, y_2, y_3, y_4\}$ and the 2-step derived algebra $\mathfrak{g}^{(2)} = \text{span}\{[e_i, e_j]\}_{1 \leq i, j \leq 4} = \text{span}\{y_3, y_4\}$ is of dimension 2. The center of $[\mathfrak{g}, \mathfrak{g}]$ is $\text{span}\{y_4\}$ of dimension 1. So by Lemma 4.3, we know that elements in center of $[\mathfrak{g}, \mathfrak{g}]$ are eigenvectors of adX , which is a very important fact in the following discussion. Similarly, we discuss the following two cases: $\lambda^2 + \eta^2 = 0$ and $\lambda^2 + \eta^2 \neq 0$.

If $\lambda^2 + \eta^2 = 0$, by (14), (15) and (16), we know that $[e_1, e_4] = [e_2, e_4] = [e_3, e_4] = 0$. Combining this with (11), (12) and (13), we conclude

$$[e_1, e_2], [e_1, e_3], [e_2, e_3] \in V_{-2\rho} = \text{span}\{e_4\},$$

which contradicts the fact that $\dim \mathfrak{g}^{(2)} = 2$. So we must have $\lambda^2 + \eta^2 \neq 0$. Notice that the center of $[\mathfrak{g}, \mathfrak{g}]$ is either $V_{-2\rho} = \text{span}\{e_4\}$ or $V_{-\rho} = \text{span}\{\eta e_1 + \lambda e_3 + \frac{\eta\theta}{\rho} e_4\}$.

Proposition 4.4. *Let the notations be as above. If e_4 lies in the center of $[\mathfrak{g}, \mathfrak{g}]$, then \mathfrak{g} admits no left-invariant non-Killing conformal vector fields.*

Proof. Since e_4 is in the center of $[\mathfrak{g}, \mathfrak{g}]$, we have $[e_1, e_4] = [e_2, e_4] = [e_3, e_4] = 0$.

Case 1. $\eta = 0$. Then $\lambda \neq 0$ since $\lambda^2 + \eta^2 \neq 0$.

First, we claim that $[e_1, e_3]$ and $[e_2, e_3]$ are non-zero. Otherwise, for example, $[e_1, e_3] = 0$, then by (12) and $\lambda \neq 0, \eta = 0$, we have $[e_2, e_3] = 0$, which means e_3 also lies in the center of $[\mathfrak{g}, \mathfrak{g}]$. This is a contradiction to the fact that center of $[\mathfrak{g}, \mathfrak{g}]$ is of dimension 1.

Secondly, we claim that $[e_1, e_3], [e_2, e_3]$ are linearly independent, so they are not the eigenvectors of adX . Otherwise, there is a non-zero $t \in \mathbb{R}$ such that $[e_1, e_3] = t[e_2, e_3]$. Then by (12) and (13), we have

$$adX([e_1, e_3]) = (-2\rho - \frac{\lambda}{t})[e_1, e_3] \quad \text{and} \quad adX([e_2, e_3]) = (-2\rho + \lambda t)[e_2, e_3],$$

so $-2\rho - \frac{\lambda}{t} = -2\rho + \lambda t$, which means $t^2 = -1$. It is impossible. So they are linearly independent. Suppose $[e_1, e_3]$ (or $[e_2, e_3]$) is an eigenvector of adX , from (12) (or (13)), it is easy to see that they are linearly dependent.

Finally, since $\dim \mathfrak{g}^{(2)} = 2$, we have $\mathfrak{g}^{(2)} = \text{span}\{e_4, [e_1, e_3]\} = \text{span}\{e_4, [e_2, e_3]\}$. Let $[e_2, e_3] = ke_4 + l[e_1, e_3]$, ($k, l \in \mathbb{R}, kl \neq 0$). By the action of adX , we have $\lambda(1 + l^2) = -\lambda lk = 0$, which violates the hypothesis.

Case 2. $\eta \neq 0$. Using (11), (12), (13) and the fact that $\dim \mathfrak{g}^{(2)} = 2$, one can similarly follow the calculation of Case 1 to prove Case 2. Here, we just give a sketch of the proof.

Firstly, we prove that $[e_1, e_2], [e_1, e_3]$ are both non-zero because of $\dim \mathfrak{g}^{(2)} = 2$.

Secondly, we prove that $[e_1, e_2], [e_1, e_3]$ are linearly independent, hence neither $[e_1, e_2]$ nor $[e_1, e_3]$ is the eigenvector of adX .

Finally, we have $\mathfrak{g}^{(2)} = \text{span}\{e_4, [e_1, e_2]\} = \text{span}\{e_4, [e_1, e_3]\}$. Let $[e_1, e_3] = ke_4 + l[e_1, e_2]$, ($k, l \in \mathbb{R}$, $kl \neq 0$). By the action of adX , we conclude that $[e_1, e_3]$ is an eigenvector of adX , which is a contradiction.

So for this case, \mathfrak{g} admits no left-invariant non-Killing conformal vector fields. ■

Similar to Proposition 4.4, we have the following proposition.

Proposition 4.5. *Let the notations be as above. If $v = \eta e_1 + \lambda e_3 + \frac{\theta\eta}{\rho} e_4$ lies in the center of $[\mathfrak{g}, \mathfrak{g}]$, then \mathfrak{g} admits no left-invariant non-Killing conformal vector fields.*

Proof. Since $v = \eta e_1 + \lambda e_3 + \frac{\theta\eta}{\rho} e_4$ lies in the center of $[\mathfrak{g}, \mathfrak{g}]$, we have

$$[v, e_1] = -\lambda[e_1, e_3] - \frac{\theta\eta}{\rho}[e_1, e_4] = 0, \tag{20}$$

$$[v, e_2] = \eta[e_1, e_2] - \lambda[e_2, e_3] - \frac{\theta\eta}{\rho}[e_2, e_4] = 0, \tag{21}$$

$$[v, e_3] = \eta[e_1, e_3] - \frac{\theta\eta}{\rho}[e_3, e_4] = 0, \tag{22}$$

$$[v, e_4] = \eta[e_1, e_4] + \lambda[e_3, e_4] = 0. \tag{23}$$

Since $\lambda^2 + \eta^2 \neq 0$, we have the following cases:

Case 1. $\eta = 0$. Then $\lambda \neq 0$. For this case, we have $v = \lambda e_3$, then $[e_1, e_3] = [e_2, e_3] = [e_3, e_4] = 0$. Then there is a contradiction similar to the discussion in Proposition 4.4 for $[e_1, e_4], [e_2, e_4]$.

Case 2. $\eta \neq 0$. In this case, by (20), (21), (22) and (23) we obtain $[e_1, e_3] = -\frac{\theta}{\rho}[e_3, e_4]$, $[e_1, e_4] = -\frac{\lambda}{\eta}[e_3, e_4]$, $[e_3, e_4] = \frac{\lambda}{\eta}[e_2, e_3] + \frac{\theta}{\rho}[e_2, e_4]$. By these relations and (13), (15), (16), we have

$$adX([e_2, e_3]) = -2\rho[e_2, e_3] + \frac{\theta\lambda}{\rho}[e_3, e_4], \tag{24}$$

$$adX([e_2, e_4]) = -3\rho[e_2, e_4] - \frac{1}{\eta}(\lambda^2 + \eta^2)[e_3, e_4], \tag{25}$$

$$adX([e_3, e_4]) = -3\rho[e_3, e_4] + \eta[e_2, e_4]. \tag{26}$$

Furthermore, we get a contradiction similar to the discussion in Proposition 4.4 for $[e_2, e_4], [e_3, e_4]$. Summing up, we have proved Theorem 1.2. ■

Remark 4.6. (Yamabe soliton) A vector field X on a pseudo-Riemannian manifold (M, g) is called a *Yamabe soliton* vector field if $L_X g = 2(R - \lambda)g$, where L_X is the Lie derivative, R is the scalar curvature of the metric g and λ is a constant. It plays an important role in exploring the Yamabe flow (see [2, 3, 4, 6, 14]). Note that the scalar curvature of any Lorentzian Lie group is a constant. So by the definitions of a conformal vector field and a Yamabe soliton vector field, any left-invariant non-Killing conformal vector field is a Yamabe soliton vector field.

Remark 4.7. (Some notes on the Lie algebras in Theorem 1.2) Denote the Lie algebras in Theorem 1.2 defined by the brackets in

- (1) the first case by $\mathfrak{A}(k, \alpha, \beta, \gamma, \delta)$, where γ, δ are arbitrary and $k\alpha\beta \neq 0$;
- (2) the second case by $\mathfrak{B}(k, \alpha, \gamma, \delta)$, where $k\alpha\gamma\delta \neq 0$;
- (3) the third case by $\mathfrak{C}(l, m, n, \alpha, \delta)$, where δ is arbitrary and $\alpha(l^2 + m^2 + n^2) \neq 0$;
- (4) the fourth case by $\mathfrak{D}(\alpha, \beta, \gamma, \delta)$, where γ, δ, β are arbitrary and $\alpha \neq 0$.

Clearly \mathfrak{A} and \mathfrak{D} have non-isomorphic derived algebras, thus they are non-isomorphic to each other as Lie algebras.

Lemma 4.8. *For given k, α, γ and arbitrary $\delta \neq 0$, $\mathfrak{B}(k, \alpha, \gamma, \delta)$ is isomorphic to $\mathfrak{A}(k, \alpha, \gamma, 0, 0)$.*

Proof. For any δ , the Lie algebra $\mathfrak{B}(k, \alpha, \gamma, \delta)$ is isomorphic to $\mathfrak{B}(k, \alpha, \gamma, 0)$ (here, we allow $\delta = 0$). In fact, set

$$e_1' = e_1 + \frac{\delta}{\alpha}e_4, \quad e_2' = e_2, \quad e_3' = e_3, \quad e_4' = e_4, \quad e_5' = e_5.$$

Then the non-zero brackets are

$$\begin{aligned} [e_2', e_3'] &= ke_4', & [e_1', e_5'] &= \alpha e_1', & [e_2', e_5'] &= \alpha e_2' + \gamma e_3', \\ [e_3', e_5'] &= -\gamma e_2' + \alpha e_3', & [e_4', e_5'] &= 2\alpha e_4', \end{aligned}$$

where $k\alpha\gamma \neq 0$. This is $\mathfrak{B}(k, \alpha, \gamma, 0)$.

In the Lie algebra $\mathfrak{A}(k, \alpha, \gamma, 0, 0)$, set $\tilde{e}_1 = e_3, \tilde{e}_2 = e_1, \tilde{e}_3 = e_2, \tilde{e}_4 = e_4, \tilde{e}_5 = e_5$. Then the non-zero brackets are

$$\begin{aligned} [\tilde{e}_2, \tilde{e}_3] &= k\tilde{e}_4, & [\tilde{e}_1, \tilde{e}_5] &= \alpha\tilde{e}_1, & [\tilde{e}_2, \tilde{e}_5] &= \alpha\tilde{e}_2 + \gamma\tilde{e}_3, \\ [\tilde{e}_3, \tilde{e}_5] &= -\gamma\tilde{e}_2 + \alpha\tilde{e}_3, & [\tilde{e}_4, \tilde{e}_5] &= 2\alpha\tilde{e}_4, \end{aligned}$$

where $k\alpha\gamma \neq 0$. Then the linear map φ defined by $\varphi(e_i') = \tilde{e}_i$ is an isomorphism between $\mathfrak{B}(k, \alpha, \gamma, 0)$ and $\mathfrak{A}(k, \alpha, \gamma, 0, 0)$. ■

By the isomorphisms of Lemma 4.8, we have a family of Lorentzian metrics on $\mathfrak{B}(k, \alpha, \gamma, 0) \cong \mathfrak{A}(k, \alpha, \gamma, 0, 0)$. The matrices of the family of Lorentzian metrics are defined by

$$\langle \cdot, \cdot \rangle_\delta = \begin{pmatrix} 1 & 0 & 0 & 0 & -\frac{\delta}{\alpha} \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 \\ -\frac{\delta}{\alpha} & 0 & 0 & -1 & 0 \end{pmatrix}, \tag{27}$$

and the corresponding left-invariant non-Killing conformal vector field is a non-zero constant multiple of $\delta e_1' - \frac{\delta^2}{2\alpha}e_4' + \alpha e_5'$ with respect to each δ . We have the following conjecture.

Conjecture 4.9. *For given k, α, γ , the metrics $\langle \cdot, \cdot \rangle_\delta$ on the Lie algebra $\mathfrak{B}(k, \alpha, \gamma, 0)$ are non-isometric to each other.*

For the study on isometry, we refer to [9], [10].

In summary, we can say that the Lie algebras listed in Theorem 1.2 can be isomorphic to each other. One can distinguish them by [11]. But the isomorphism will induce different metrics on the Lie algebras. Here, we use the notation in this paper to keep the metric form (5) simplest.

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